



A new Neural Network architecture for automatic Urban Change Detection from Satellite Imagery

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One of the most challenging problems addressed by the remote sensing community in current years is the development of effective data processing techniques for images acquired with the last generation of very high spatial resolution sensors.

Information on temporal dynamics of land cover in and around urban areas is needed for a variety of purposes:

- •housing planning policy
- •transportation planning policy
- •environmental studies





The aim of this research is to develop a Change Detection Algorithm in order to obtain the accuracies required by typical applications.

• A new method for urban change detection that greatly reduces the human effort needed to analyze the imagery:

NAHIRI: Neural Architecture for HIgh Resolution Imagery

Change Detection algorithm based on Neural Networks able to exploit in parallel both the multi-band and the multi-temporal data to discriminate between real changes and false alarms.



A. BU	Asantas Hasing

	Site Inform	ation		Image Inf	formation	
Data Set 1	Location	Dimension (km ²)	Acquisition Date	Satellite	Spatial Res. (m)	Dimension (pixels)
TEST AREA 1	Tor Vergata Campus,	3.7	May 29, 2002	QuickBird	2.8	706 x 729
	Rome, Italy		March 13, 2003			
TEST AREA 2	Boulder,	280	July 5, 1992	Landsat	30	664 x 432
	Colorado, U.S.A.		August 17, 1996			
TEST AREA 3	Boulder,	0.4	August 14, 2002	QuickBird	0.6	1300 x 800
	Colorado, U.S.A.		July 6, 2004			
TEST AREA 4	Boulder,	6.2	October 23, 2003	QuickBird	2.4	1382 x 800
	Colorado, U.S.A.		October 15, 2005			



NAHIRI Flow Chart



1. Choice of the inputs of the NNs



 $R_{i} = \left| B_{iB} / B_{iG}, B_{iB} / B_{iR}, B_{iB} / B_{iNIR}, B_{iG} / B_{iR}, B_{iG} / B_{iNIR}, B_{iR} / B_{iNIR} \right|^{T}$

- 2. Topology of NN1 and NN2
 - **Output 4 Classes:**
 - Man Made
 - **Vegetation**
 - Soil ۲
 - Water

Multi-layer 6-12-12-4 Perceptron

3. Change Map = MAP1- MAP2

4. Multi-temporal Operator

$|Log\{R_1(k)\}-Log\{R_2(k)\}|$

5. Topology of NN3: Change Mask **Output - 2 Classes:**

Change

No Change Multi-layer 6-12-12-2 Perceptron

6. AND Gate: NAHIRI CD



NN1 and NN2 Topology



Test Area 1: Campus of the Tor Vergata University





The campus of the Tor Vergata University is located in the upper part of the image. (2002)







Change Map

		2003	
2002	Vegetation	Man-made	Soil
Vegetation	Gray	Cyan	Orange
Man-made	Green	Gray	White
Soil	Red	Yellow	Gray



Change Mask













(2002)















Test Area 2: Boulder, Colorado, USA



The Boulder study area is located northwest of Denver, Colorado, U.S.A.



Boulder Area (1992)

Boulder Area (1996)

Test Area 2: Boulder, Colorado, USA

NAHIRI CD

Boulder Area (1992)

Boulder Area (1996)

NAHIRI

PCC

Test Area 2: Boulder, Colorado, USA

							1996																				
1992	Green	Red	Blue	Yellow	Magenta	Cyan	Dark Green	Brown	Dark Blue	Orange	White	Black	Gray	Total pixel	Excl. Error (%)		NA	H	IR	T				C	ha	ng	e
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White	0	0	0	0	D			O	0	0	1				0	2	0	0	0	0	0	0	0	0	0	0	0
Black	0	0	0	0	n	0	n	n	Ο	0	0	1	0	0	0		0	0	0	0	0	0	0	0	0	0	0
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Test Area 3: Boulder, Colorado, USA

							NAHIRI]				ТА	TT								
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Cyan	133	6	0	3	0	55	0	0	0	0	0	0	33	175	76.1	ı _	P	ost Classi	fication C	omparison							Excl.
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Dark Blue	0	0	0	0	0	0				0			0	0	-	3	0	0	0	0	0	0	77	0	1085	6905	2.6
Orange	1865	42	0	556	0				0	0	11			35697	100		0	0	0	0	0	0	0	0	8	19	100
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Boulder, called Rocky Flats, was Test Area 4: Boulder, Colorado, USA chosen for the facility.

the negative Test Area 4 (about 2005) direction.

Man-made	TIes	tt ANGEEN 44	(21005))	White
Water			Gray	Black
Soil	Red		Brown	Gray

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Conclusions

We developed a novel method based on a Neural Network Architecture for change detection that is able to process simultaneously multi-temporal and multi-band data.

			NAHIRI	РСС
	Location	Spatial Res. (m)	K-Coe	fficient
Test Area 1	Tor Vergata Campus, Rome, Italy	2.8	0.783	0.444
Test Area 2	Boulder, Colorado, U.S.A.	30	0.881	0.619
Test Area 3	Boulder, Colorado, U.S.A.	0.6	0.722	0.568
		Mean	0.795	0.544

The mean of the *K-Coefficient* ranges from 0.544 in the case of PCC to 0.795 (NAHIRI) over very high and high resolution optical imagery.

Thank you for your attention!

Test Area 3